

Time Series Modeling of Start-Stop Battery Electric Vehicle Charging





INTRODUCTION

- The Battery Electric Vehicles (BEVs) has reached maturity and expected to replace the Internal Combustion Engine (ICE) Vehicles.
- Relying solely on stored energy from electric charges in their battery packs, BEVs propel their electric motors without the need for traditional combustion engines.
- Meeting this growing demand requires electricity utility providers to enhance electricity generation capabilities and upgrade distribution grids for BEVs charging stations.

INTRODUCTION

- Manufacturers of BEVs and charging stations typically record charging sessions at start and stop points. This data can be valuable for forecasting electricity demand, as it provides insights into usage patterns.
- BEV charging data often exhibits non-stationary and unstable characteristics, posing significant challenges for forecasting (Dokur et. al).
- The raw data need to be transformed into a continuous time series format for effective modeling of charging behavior, enabling trend and seasonality forecasting.

METHODOLOGY

- Secondary data for this study was sourced from the My Electric Avenue project in the UK where 209 Nissan Leaf BEVs were leased to participants and its usage behavior is recorded.
- Using data from January 1, 2014 to December 15, 2014, the transformation involves counting simultaneous charging by augmenting data between start and stop times.
- The final transformed data will be suitable to be used in the LSTM model for modeling and forecasting electric load demand from BEV during active charging session.

METHODOLOGY



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METHODOLOGY

 The hidden LSTM layer is structured as a sequential single layer, encompassing 125 units of LSTM cells. In the training process, the data was divided into sequences of 60 data points, each associated with a single expected output.



$$f_t = \sigma_g \big(W_f * x_t + U_f * h_{t-1} + b_f \big)$$

$$i_t = \sigma_g(W_i * x_t + U_i * h_{t-1} + b_i)$$

$$o_t = \sigma_g(W_o * x_t + U_o * h_{t-1} + b_o)$$

$$\dot{c}_t = \sigma_c (W_c * x_t + U_c * h_{t-1} + b_c)$$

$$c_t = f_t \cdot c_{t-1} + i_t \cdot \acute{c}_t$$

 $h_t = o_t \cdot \sigma_c(c_t)$

RESULTS







CPU-A, CPU-L and Mean, MAPE CPU-A, CPU-B, Mean, Loss Function - CPU-A - CPU-L - Mean - CPU-A - CPU-L - Mean 2.50% 1.00E-04 8.00E-05 2.00% Loss function MAPE, % 6.00E-05 1.50% 4.00E-05 1.00% 50 10 20 30 40 10 20 30 40 Epochs Epochs

CONCLUSIONS

- The transformed data from BEVs has been found suitable for time series modeling using the LSTM method.
- This indicates that the data retains the necessary patterns and characteristics, making it effective for accurately predicting future trends in BEVs charging behavior through advanced modeling techniques like LSTM.
- The LSTM method proposed in this study achieved:
 - CPU-A: MAPE of 1.38%, RMSE of 0.51 (after 20 epochs)
 - CPU-L: MAPE of 1.19%, RMSE of 0.51 (after 20 epochs)

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