

Development of a Cloud-Based Road Surface Quality Assessment System

Lim Ka Quan, **Dr. Nor Azuana Ramli**, and Dr. Mohd Radhie Mohd Salleh **Centre for Mathematical Sciences, Universiti Malaysia Pahang Al-Sultan Abdullah** and I Net Spatial Sdn. Bhd.





INTRODUCTION

High-quality road surfaces are essential for safety and economic well-being.

In 2023, Malaysia recorded approximately 600,000 road accidents, resulting in 6,443 fatalities—equivalent to an average of 18 deaths per day.

A study by the Malaysian Institute of Road Safety Research (MIROS) found that road accidents were mainly caused by human behavior, followed by the design, condition of road infrastructure, and vehicles' condition.

There is still a potential to reduce the number of road accidents and injuries by improving road surfaces, thereby fostering sustainable cities and communities.

Key 🌤 Road deaths per 100,000 people 👫 Road quality score /7 🚊 Traffic level 💺 Seatbelt wearing percentage Difference Attribution of road traffic deaths to alcohol 📀 Max speed limit in towns (kph) 😵 Motorway speed limit (kph) 🖤 Road safety score /10

Country	*@	4	A	Ġ.	Ď	~	۲	$\mathbf{\nabla}$
1 Netherlands	3.98	6.4	89.4	96%	11%	50	130	7.86
2 Norway	2.12	4.5	92.6	95%	13%	50	110	7.47
3 Sweden	3.14	5.3	98.2	97%	24%	50	120	7.42
3 Estonia	4.46	4.7	84	95%	10%	50	120	7.42
5 Spain	3.91	5.7	105.2	88%	12%	50	120	7.20
6 United Kingdom	3.21	4.9	133.8	98%	13%	48	112	7.09
6 Finland	3.89	5.3	82.6	94%	24%	50	120	7.09
8 Iceland	2.05	4.1	88.9	90%	14%	50	90	7.03
9 Germany	3.78	5.3	105.1	98%	7%	50	447	6.98
10 Japan	3.60	6.1	133.7	95%	6%	60	120	6.71
11 Luxembourg	4.07	5.5	108.9	92%	14%	50	130	6.21
11 Portugal	8.20	6.0	110.9	95%	29%	50	120	6.21
13 Lithuania	8.14	4.8	89.6	94%	10%	50	130	6.16
14 Israel	3.91	4.9	154.1	88%	4%	50	120	6.15
15 Croatia	7.95	5.6	96.1	58%	24%	50	130	5.38
15 Ireland	3.13	4.4	149.5	91%	39%	50	120	5.11
17 Chile	14.91	5.2	128.2	50%	13%	50	120	4.95
18 Hungary	7.74	4.0	126	81%	7%	50	130	4.84
19 Slovenia	5.05	4.9	99.2	82%	32%	50	130	4.78
20 Poland	9.38	4.3	114.4	94%	13%	50	140	4.34
21 Canada	5.34	5.0	140.1	95%	30%	80	120	4.29
22 Serbia	7.47	3.5	111.7	66%	17%	50	130	4.18
23 Malaysia	22.48	5.3	168.4	48%	0%	60	110	4.07
24 Mexico	12.78	4.5	175.4	59%	20%	50	110	3.96
25 Greece	8.31	4.6	133.1	72%	25%	50	130	3.85
26 United States	12.67	5.5	152.2	90%	29%	89	137	2.53
27 Argentina	14.06	3.6	175	44%	17%	60	130	1.65



Common Road Surface Defects



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OBJECTIVES

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To design a cloud-based architecture that can process and respond numerous of data in a short period of time by applying Digital Ocean cloud services.

To identify road surface quality defections effectively by using of YOLO.

To develop a cost-effective system that optimizes accuracy for real-time processing by implementing data augmentation, and confusion matrix-based evaluation approach. Developing a cloud-based road surface quality assessment system ensures safer and more reliable transportation infrastructure for all.

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METHODOLOGY

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Data for this study was collected from site visits and the Internet, such as Google Images.

2 phases in data preprocessing: video preprocessing (frame resizing and video frame extraction) and image preprocessing (labelling, data augmentation, and image resizing).

Dataset was partitioned into two subsets: 80% (6400 images) for the training phase and 20% (1600 images) for testing

Cloud-based road surface quality assessment system using the YOLOv8 model since it is well-suited for use in a cloud-based system, where the computational resources can be scaled to meet the demands of the application

The effectiveness of the model was assessed using common object detection metrics, such as precision, recall, and the average mean precision (mAP).

RESULTS

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CRMN0539.MP4



Video Recorded using Dashcam

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Extracted video frames by using Python





Results of preprocessing

The number of epochs for model development was 200, and the batch size was 16. By default, the model training will trigger early stopping if there is no improvement in the last 50 epochs to avoid overfitting; thus, this model stopped at epoch 153. The best result was obtained at epoch 103.



Confusion matrix

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Overall Results for YOLOv8 Model Training



The model's speed: it takes 0.7 milliseconds (ms) for preprocessing, 7.5 ms for inference, 0.0 ms for loss computation, and 1.5 ms for postprocessing per image.

This efficient processing is a key feature for road anomaly detection in dashcam footage applications, instilling confidence in the model's applicability

The 0.0 ms loss time confirms that loss computation, typically used during training to optimize the model, is not a factor during the evaluation phase. This breakdown underscores that the model is optimized for real-time or nearreal-time analysis, with the majority of the processing time dedicated to inference, the task of detecting objects in the image.

Preprocessing and postprocessing times are relatively minimal, suggesting that the model efficiently prepares the data for analysis and processes the results.



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Ø Results	The Trans Schooling 1 to 8 of 8 entities	Image: Second	Time

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Results based on file uploaded using DigitalOcean cloud

CONCLUSION

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This study aims to make road defect detection faster, more accurate, and costeffective. We used GIS technology and a deep learning model to accurately locate and classify road surface defects. Our dataset included 4,000 images collected from various sources. We employed a pre-trained model to detect and classify defects and assessed its accuracy.

Our method could significantly benefit local government departments and enhance public safety by enabling timely and reliable identification of road surface defects.

This research has the potential to improve road safety and reduce maintenance time, contributing to public safety and overall road conditions.

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Thank you!

